

Announcements

1) Entering a vector into
webwork: (# 7)

$\langle 5, 2 \rangle$ is an example

2) Careful with little
errors!

3) New HW - appearing
later today, due next
Wednesday

Example 1: Describe all

solutions to

$$5x_1 - 2x_2 + x_3 - 6x_4 = 1$$

$$-x_1 + 6x_2 + 10x_3 + 2x_4 = -1$$

Matrix

$$\begin{bmatrix} 5 & -2 & 1 & -6 & 1 \\ -1 & 6 & 10 & 2 & -1 \end{bmatrix}$$

ref

$$\begin{bmatrix} 1 & 0 & 13/14 & -8/7 & 1/7 \\ 0 & 1 & 5/28 & 1/7 & -1/7 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 13/14 & -8/7 & 1/7 \\ 0 & 1 & 5\frac{1}{28} & 1/7 & -1/7 \end{bmatrix}$$

what does this say?

$$x_1 + \frac{13}{14} x_3 - \frac{8}{7} x_4 = \frac{1}{7}$$

$$x_2 + 5\frac{1}{28} x_3 + \frac{1}{7} x_4 = -\frac{1}{7}$$

So

$$x_1 = \frac{1}{7} - \frac{13}{14} x_3 + \frac{8}{7} x_4$$

$$x_2 = -5\frac{1}{28} x_3 - \frac{1}{7} x_4 - \frac{1}{7}$$

The most general solution is then


$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} \frac{1}{7} - \frac{13}{14}x_3 + \frac{8}{7}x_4 \\ -\frac{1}{7} - \frac{5}{28}x_3 - \frac{1}{7}x_4 \\ x_3 \\ x_4 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{7} \\ -\frac{1}{7} \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -\frac{13}{14} \\ -\frac{5}{28} \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} \frac{8}{7} \\ -\frac{1}{7} \\ 0 \\ 1 \end{bmatrix}$$

How does the row-reduced matrix correspond to the three cases for solutions?

1) **No solution:** you will see a row of all zeros except for the last entry

e.g.
$$\begin{bmatrix} 1 & 0 & 6 \\ 0 & 0 & 1 \end{bmatrix}$$



no solution

2) Unique solution:

every row either is all zeros or has exactly one nonzero entry (which is a one) in all columns to the left of the last one.

e.g.

$$\begin{bmatrix} 1 & 0 & 0 & 5 \\ 0 & 1 & 0 & 6 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

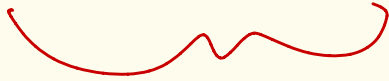
unique solution

3) Infinitely many solutions

any other situation! In particular, you will have no rows that are all zeros except for the last number and at least one row will have two nonzero entries to the left of the last column.

e.g. example 1 today or

$$\begin{bmatrix} 1 & 0 & 5 & 3 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$



infinitely many solutions

How to get solutions faster

Homogeneous equations

A linear equation $Ax = b$

is called **homogeneous** if

b is the zero vector
(all coordinates zero).

Such an equation always has
at least one solution, which
is the **trivial solution** where
 x is the zero vector.

Example 2:

$$\begin{bmatrix} -1 & 3 & 0 \\ 6 & 8 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

is a homogeneous equation.

Note the solution $x_1 = x_2 = x_3 = 0$.

But

$$\begin{bmatrix} 3 & 18 \\ -11 & 10 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$$

is not homogeneous.

Briefly, if A is
an $m \times n$ matrix, x
is an n -vector, and
 $\vec{0}$ denotes the m -vector
with zeroes in all entries,
then a homogeneous equation
is of the form

$$Ax = \vec{0}$$

Given vectors v_1, v_2, \dots, v_k
in \mathbb{R}^n , we define a
linear combination of

v_1, v_2, \dots, v_k to be any vector
of the form

$$a_1 v_1 + a_2 v_2 + \dots + a_k v_k$$

where a_1, a_2, \dots, a_k are
numbers.

Example 3:

$$\text{Let } v_1 = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$\text{and } v_2 = \begin{bmatrix} -1 \\ 8 \end{bmatrix}.$$

The vector

$$v = \begin{bmatrix} 0 \\ 28 \end{bmatrix} \text{ is a linear}$$

combination of v_1 and v_2 since

$$v_1 + 3v_2 = \begin{bmatrix} 3 \\ 4 \end{bmatrix} + \begin{bmatrix} -3 \\ 24 \end{bmatrix} = \begin{bmatrix} 0 \\ 28 \end{bmatrix}$$

Span: Given vectors

v_1, v_2, \dots, v_k in \mathbb{R}^n , the

span of v_1, v_2, \dots, v_k is

equal to all vectors v

that are linear combinations

of v_1, v_2, \dots, v_k .

Example 4 : Describe the

span of

$$v_1 = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} \text{ and } v_2 = \begin{bmatrix} 6 \\ 0 \\ -2 \end{bmatrix}$$

in \mathbb{R}^3 .

The span is all vectors

of the form

$$a_1 v_1 + a_2 v_2 \text{ for}$$

numbers a_1 and a_2 .

We don't get all of \mathbb{R}^3 since we don't have enough vectors.

The span is a plane since we have two vectors and neither one is a multiple of the other.

Moreover, the plane goes through the origin since we can choose $a_1 = a_2 = 0$ and get $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ in the span.

Observations:

1) The zero vector is always in the span.

2) The vectors v_1, v_2, \dots, v_k are always in their span.

So the span of any nonzero vectors is always infinite!